

2100 SERIES



Series 2100, is a high performance, permanent magnet brush servo motor for use in various industrial direct drive or geared servo systems

- Rugged industrial construction
- Continuous torque ratings up to 53 oz.-in. —with speeds up to 6500 RPM (no load)
- Peak torque ratings up to 300 oz.-in.
- High torque-to-inertia ratio delivers maximum torque per frame size
- Superior low speed performance
- Numerous custom options available

Performance Benefits

Cleveland Motion Controls specializes in the design of high performance brush servo motors that provide efficiency, flexibility of application, and a long and trouble-free service life. Our TORQUEMASTER™ 2100 series is no exception.

With fast response, accurate control and high torque-to-inertia ratios, you can count on the TORQUEMASTER 2100 Series of brush servo motors to provide smooth operation throughout a full speed range. The 2100 Series delivers smooth and superior low speed performance, and maximum power ratings with low thermal resistance for high speed performance. In addition, with maximum torque in a smaller package, you can count on better pricing for a better overall value.

When integrated with high performance brush amplifiers, TORQUEMASTER 2100 Series brush servo motors provide effective and highly efficient motion control solutions for a wide range of applications—including factory automation, packaging, robotics, machine tools, medical instrumentation and more.

Design Features

TORQUEMASTER 2100 Series brush servo motors are rated from 18 oz.-in. to 53 oz.-in. with speeds and torque stability up to 6500 RPM. They utilize the latest in high performance permanent magnet technology, and are available in eight standard windings (as well as custom windings) to meet your most demanding applications.

Each brush servo motor in the TORQUEMASTER 2100 Series is ruggedly designed and manufactured for reliable performance.

Motors can be customized to fit your exact application with tachometers, encoders, brakes and other options.



MOTOR CHARACTERISTICS

SYMBOL		UNITS	2110	2115	2120	2130
T _C	Cont. Torque	Oz-In	18	30	38	53
T _P	Peak Torque	Oz-In	100	150	200	300
T _F	Static Friction	Oz-In	3	3	3	3
F _i	Viscous Friction	Oz-In/KRPM	0.3	0.3	0.4	0.5
T _R	Cogging Torque	Oz-In	0.3	0.5	0.5	0.5
J _M	Inertia	Oz-In-sec ²	0.0031	0.0044	0.0057	0.0083
R _{TH}	Thermal Res	Deg C/watt	6.2	5	4.5	3.8
T _{TH}	Thermal Time	Minute	10	15	15	20
t _m	Mech Time	Millisec	12.19	8.62	8.07	7.20
t _e	Elect Time	Millisec	1.9	2.1	2.1	2.2
F _C	Commutation	Factor	722	1260	1548	2116
Wt	Weight	Lbs	2.9	3.1	3.3	4.3

Note: All values at 25°C Ambient.

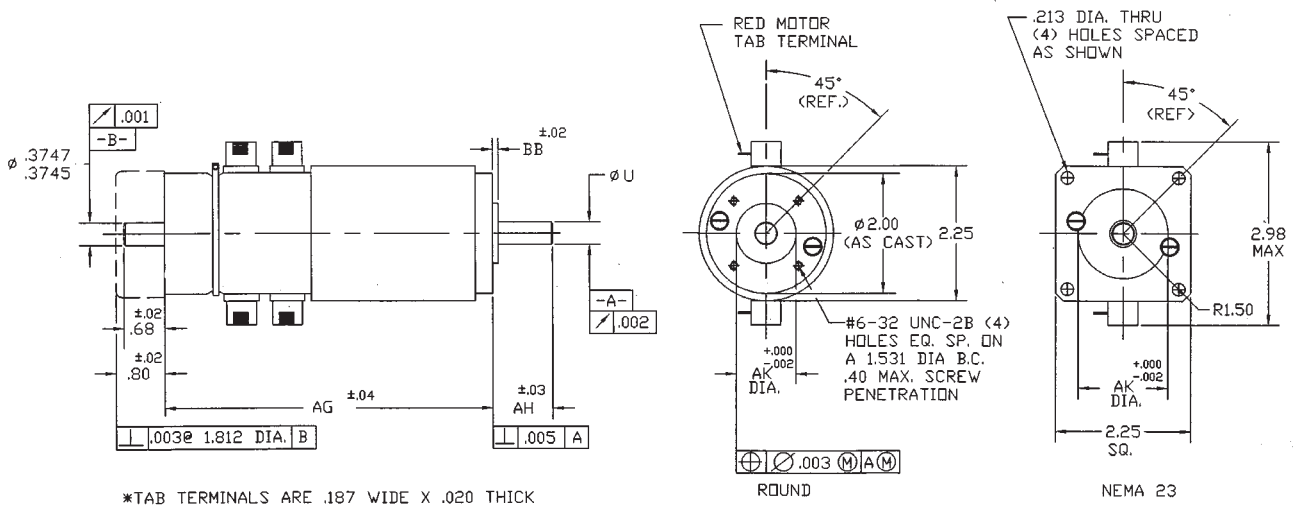
WINDING

A	K _T	Torq. Sens.	Oz-In/Amp	3.8	6.12	7.74	11.2
	R _A	Arm. Resis.	Ohms	0.40	0.52	0.60	0.80
	K _V	Back E.M.F	Volts/KRPM	2.8	4.5	5.7	8.3
	F _C /K _T	P _b	Watts	190	206	200	189
B	K _T	Torq. Sens.	Oz-In/Amp	4.7	7.48	9.46	13.6
	R _A	Arm. Resis.	Ohms	0.61	0.77	0.89	1.18
	K _V	Back E.M.F	Volts/KRPM	3.5	5.5	7.0	10.1
	F _C /K _T	P _b	Watts	154	168	164	156
C	K _T	Torq. Sens.	Oz-In/Amp	5.9	9.52	12	17.3
	R _A	Arm. Resis.	Ohms	0.97	1.25	1.44	1.92
	K _V	Back E.M.F	Volts/KRPM	4.4	7.0	8.9	12.8
	F _C /K _T	P _b	Watts	122	132	129	122
D	K _T	Torq. Sens.	Oz-In/Amp	7.4	11.9	15	21.7
	R _A	Arm. Resis.	Ohms	1.52	1.96	2.25	3.01
	K _V	Back E.M.F	Volts/KRPM	5.5	8.8	11.1	16.0
	F _C /K _T	P _b	Watts	98	106	103	98
E	K _T	Torq. Sens.	Oz-In/Amp	9.3	15	19	27
	R _A	Arm. Resis.	Ohms	2.40	3.11	3.61	4.67
	K _V	Back E.M.F	Volts/KRPM	6.9	11.1	14.0	20.0
	F _C /K _T	P _b	Watts	78	84	81	78
F	K _T	Torq. Sens.	Oz-In/Amp	11.7	18.7	23.6	34
	R _A	Arm. Resis.	Ohms	3.80	4.84	5.57	7.40
	K _V	Back E.M.F	Volts/RPM	8.6	13.8	17.4	25.1
	F _C /K _T	P _b	Watts	62	67	66	62
G	K _T	Torq. Sens.	Oz-In/Amp	14.4	23	29	42
	R _A	Arm. Resis.	Ohms	5.76	7.32	8.41	11.29
	K _V	Back E.M.F	Volts/KRPM	10.6	17.0	21.4	31.0
	F _C /K _T	P _b	Watts	50	55	53	50
H	K _T	Torq. Sens.	Oz-In/Amp	18	29	36	52
	R _A	Arm. Resis.	Ohms	9.00	11.64	12.96	17.31
	K _V	Back E.M.F	Volts/KRPM	13.3	21.4	26.6	38.4
	F _C /K _T	P _b	Watts	40	43	43	41

Note: Continuous torque specifications obtained with motor mounted to an 10" x 10" x 0.25" alum. plate at 25 C° ambient. Typical values are within ±10% of rating.

For custom designs please consult factory.
All specifications subject to change without notice.

MECHANICAL SPECIFICATIONS



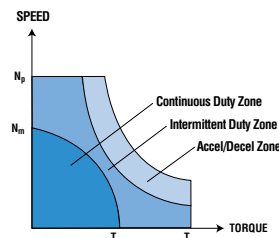
DIMENSION CHART

MOTOR	AG		U DIA.		AH		AK		BB	
	Motor Only Inches (Metric)	Motor Tach Inches (Metric)	STD	NEMA	STD	NEMA	STD	NEMA	STD	NEMA
2110	3.63 (92.2)	5.10 (129.5)	.3750/.3740	.2500/.2495	1.00	0.77	1.000	1.500	0.10	0.06
2115	4.13 (104.9)	5.60 (142.2)	.3750/.3740	.2500/.2495	1.00	0.77	1.000	1.500	0.10	0.06
2120	4.63 (117.6)	6.10 (154.9)	.3750/.3740	.2500/.2495	1.00	0.77	1.000	1.500	0.10	0.06
2130	5.63 (143.0)	7.10 (180.3)	.3750/.3740	.2500/.2495	1.00	0.77	1.000	1.500	0.10	0.06

METRIC (mm): DIMENSIONS ALL FRAME SIZES

SHAFT: DIA	8j6	MOUNTING: PILOT	25.0
LENGTH	25.0	B.C.	38.89
		HOLE SIZE	M4

TORQUE PERFORMANCE CURVES



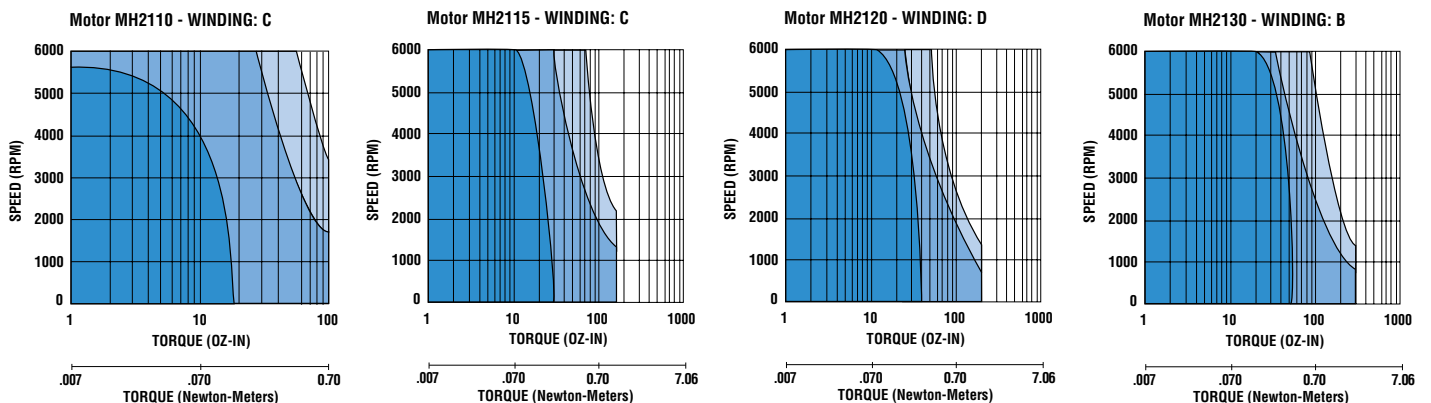
NOTE: Continuous torque specifications obtained with motor mounted to an 10"x10"x.25" aluminum plate at 25 C° ambient. Typical values are within ±10% of rating.

STANDARD WINDING SPEED/TORQUE CURVE DATA FOR SIZING A SERVO MOTOR

- Nm = Maximum speed, continuous operation
- Np = Peak speed, acceleration/deceleration and intermittent duty
- Tcs = Continuous stall torque
- Tp = Peak torque

All specifications subject to change without notice.

TORQUE PERFORMANCE CURVES



TORQUE SPEED CURVES OF OTHER WINDINGS AVAILABLE, CONSULT FACTORY.

BRUSH SERVO MOTORS

2100 SERIES

VOLTAGE EQUATION FOR MOTORS

$$\text{Volts} = \frac{K_T \times \text{RPM}}{1,350} + \frac{T \times R_A}{K_T} + V_B$$

where

K_T = torque constant, oz.-in. per amp
 T = load torque plus motor friction torque-oz.-in.
 R_A = armature resistance + brush resistance
 V_B = brush voltage drop = 2 volts

Note: For armature resistance at maximum temperature rating, multiply catalog value of R by 1.5

MOTOR TORQUE RATING VS. SPEED

$$T_R = .94K_T \left[\frac{1.30 \cdot \text{RPM} \times T_F + \text{RPM}^2 \times F_i}{R_{TH} \cdot 1,350 + 1,350,000} \right]^{1/2} T_F \cdot \frac{\text{RPM} \times F_i}{1000}$$

where

T_R = rated torque (25°C ambient)-oz.-in.
 K_T = torque sensitivity-oz.-in./amp
 R_A = armature resistance
 RPM = revolutions per minute
 T_F = static friction torque-oz.-in.
 F_i = viscous friction-oz.-in.
 R_{TH} = thermal resistance

TO FIND: Higher Torque Rating for Intermittent Duty

$$\text{Let } A = \frac{\text{total cycle time in seconds}}{\text{thermal time constant of motors in seconds}}$$

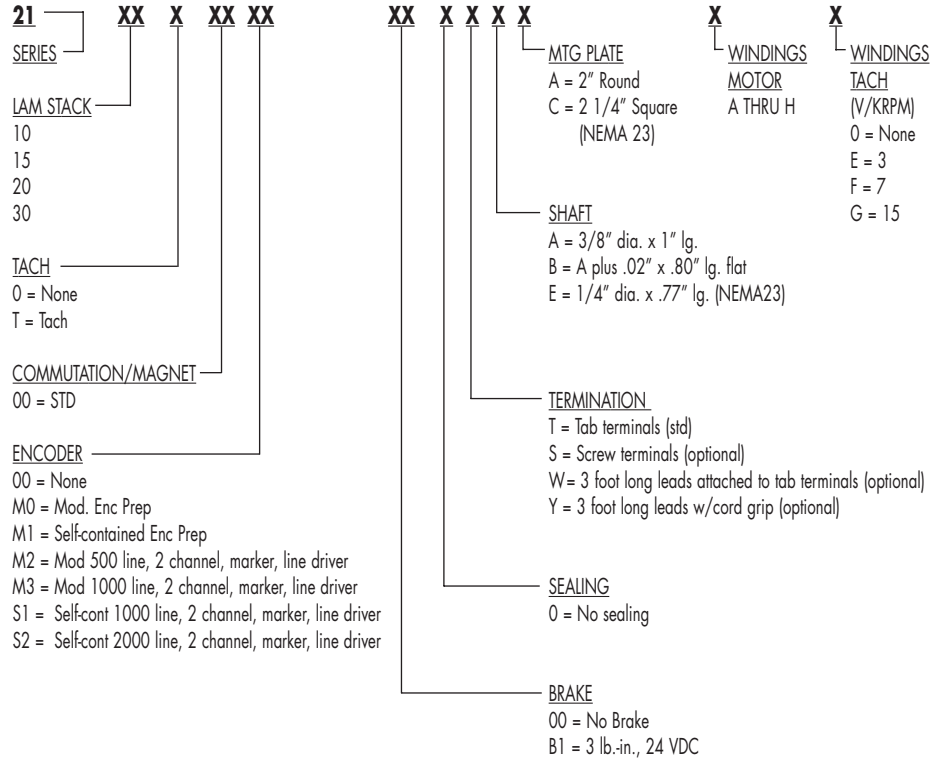
$$\text{Let } B = \frac{\text{"on" time in seconds per cycle}}{\text{thermal time constant of motor in seconds}}$$

then with T_R = Rated torque for 100% duty
 and T_{MAX} = Rated torque for intermittent duty

$$T_{MAX} = T_R \times \left[\frac{1 - e^{-A}}{1 - e^{-B}} \right]^{1/2}$$

TORQUEMASTER™

ORDERING INFORMATION (For Standard Options)



Customize The 2100 Series To Your Exact Requirements

To satisfy various applications with cost-effective solutions, 2100 Series motors are readily available with a wide range of standard capabilities. Final designs are often the result of cooperative efforts between the customer's engineering department and CMC. For assistance, call your local CMC distributor or CMC direct. We look forward to meeting your custom requirements.



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